

FIG. 1

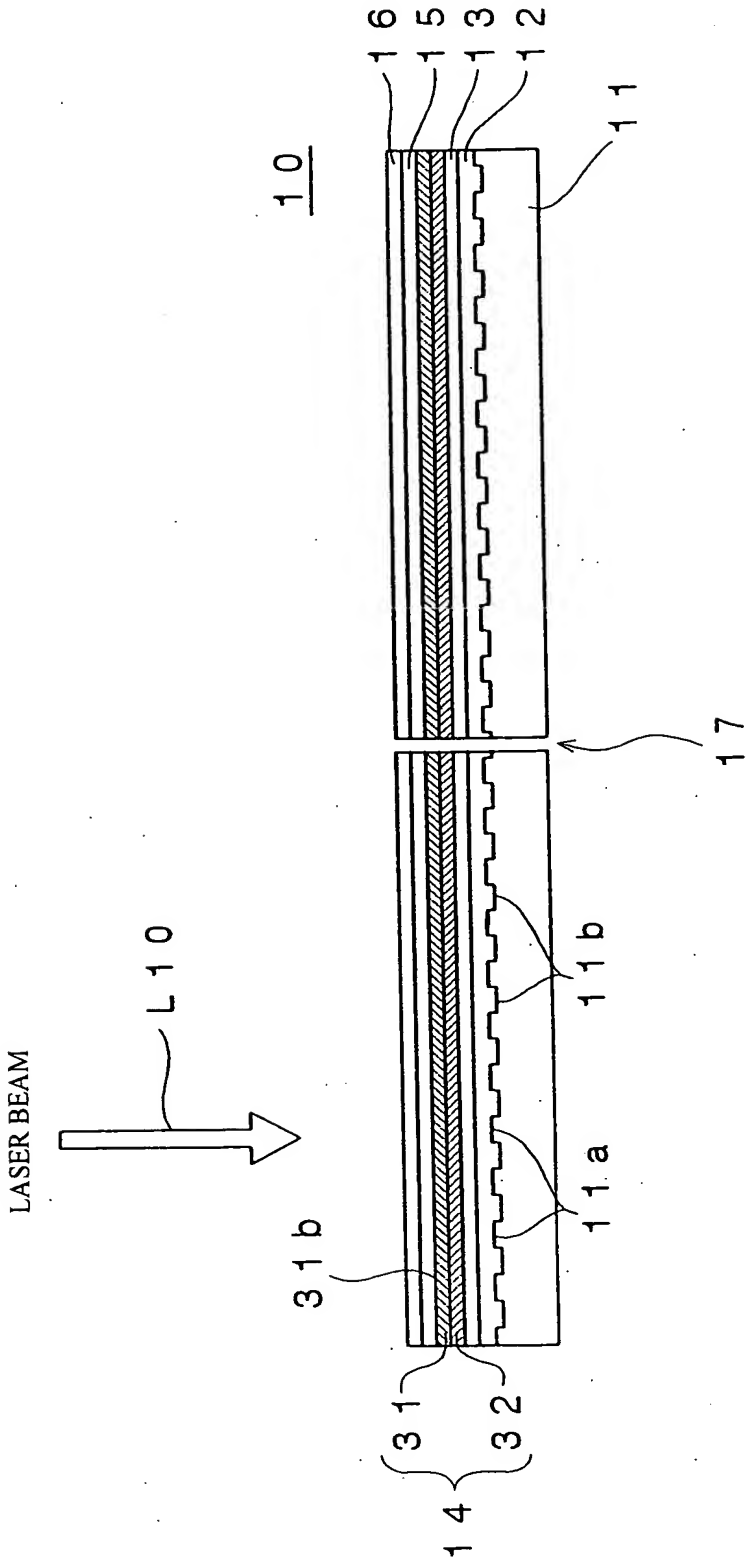
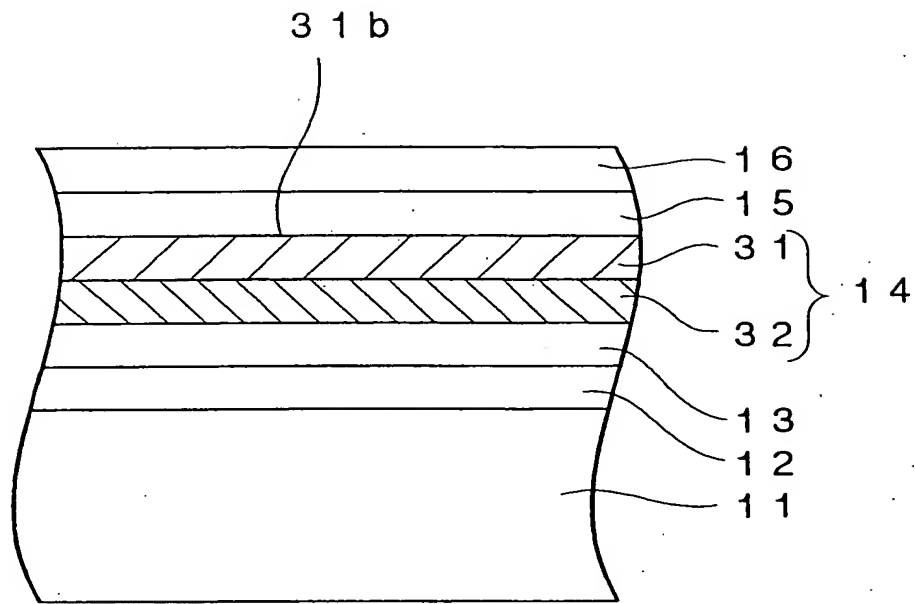
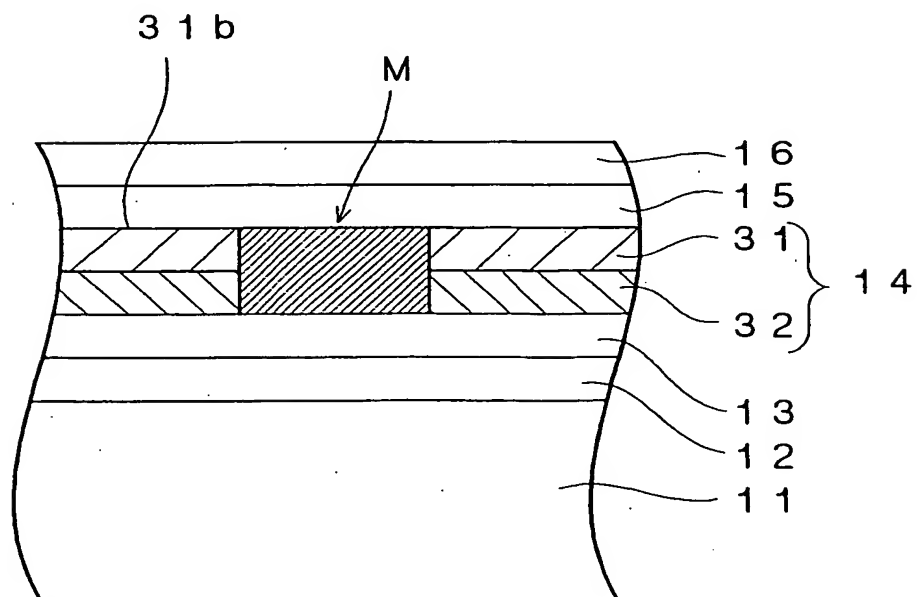


FIG. 2



(a)

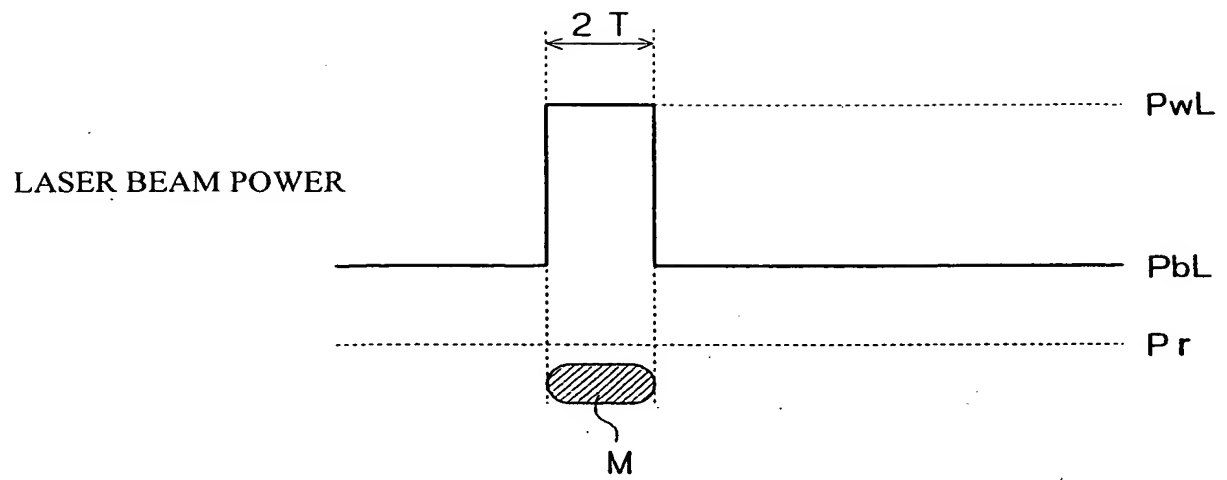


(b)

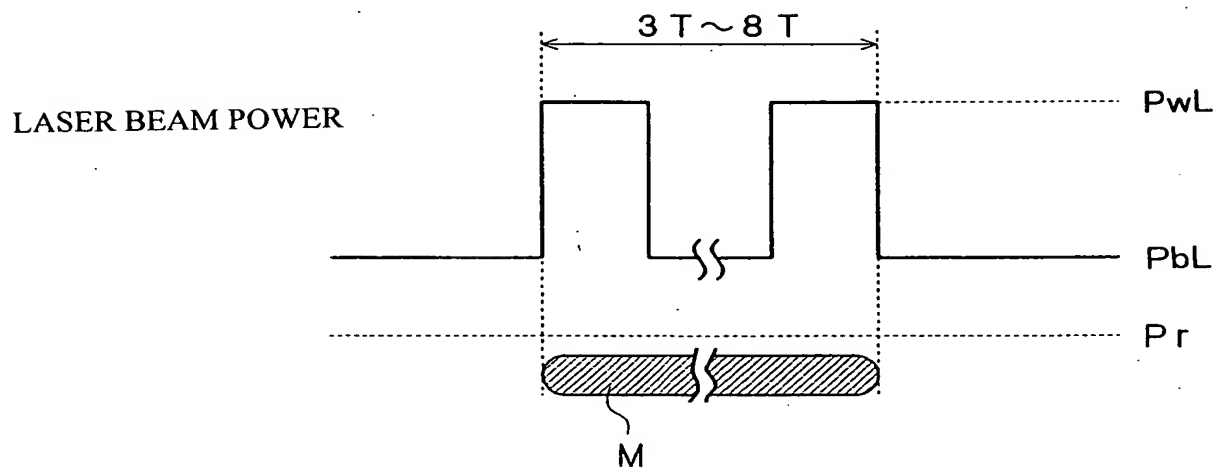
FIG. 3

		NUMBER OF PULSES						
		2T	3T	4T	5T	6T	7T	8T
LINEAR RECORDING VELOCITY ↓	LOW (VL)	1	2	3	4	5	6	7
		1	1	2	2-3	2-4	2-5	2-6
		1	1	1	2	2-3	2-4	2-5
	MEDIUM (VM)	1	1	1	1	2	2-3	2-4
		1	1	1	1	1	2	2-3
		1	1	1	1	1	1	2
	HIGH (VH)	1	1	1	1	1	1	1

FIG. 4



(a)



(b)

FIG. 5

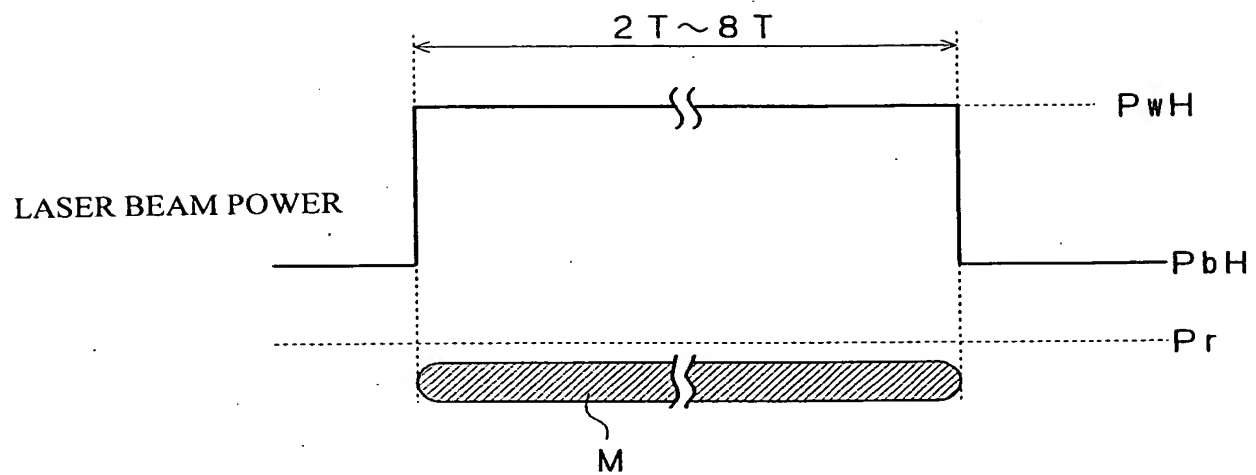
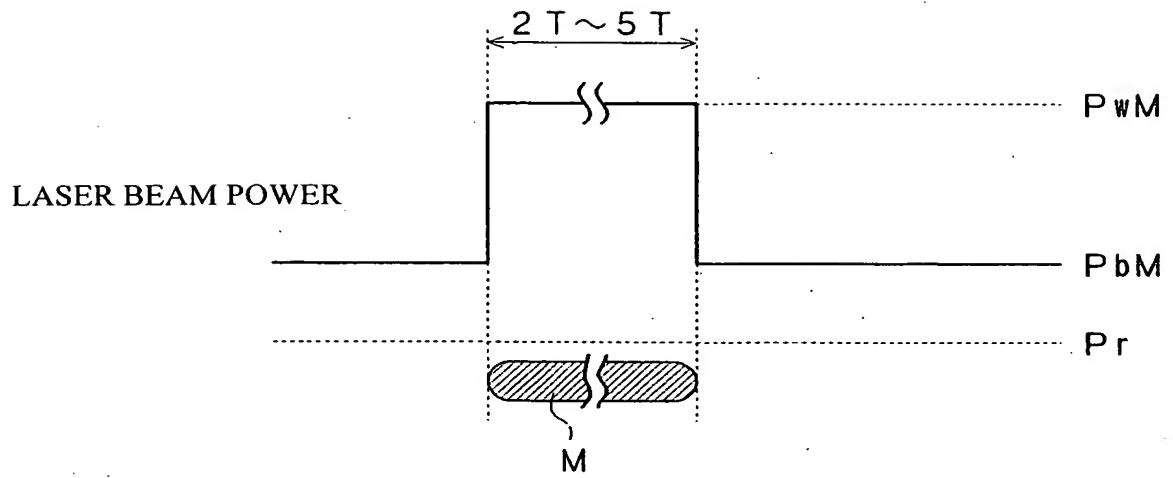
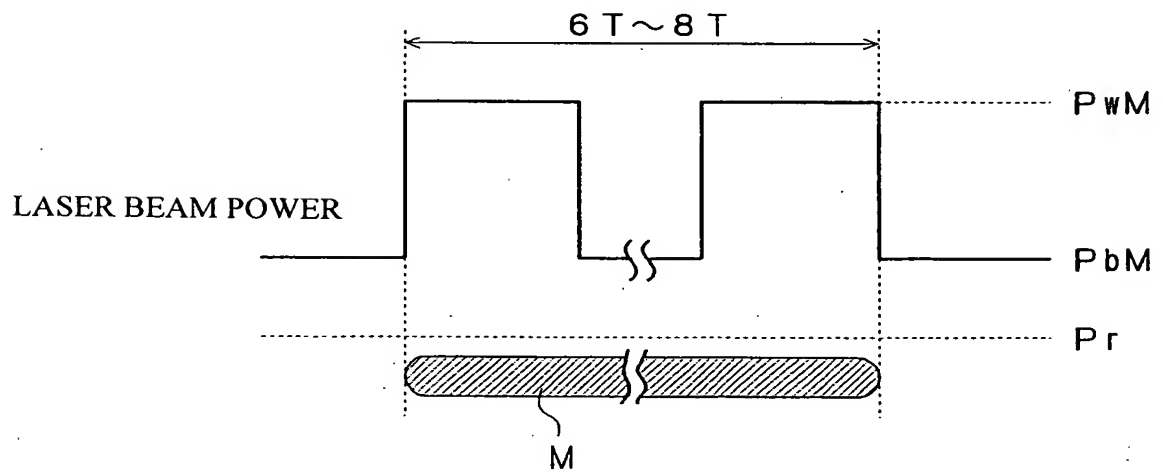


FIG. 6



(a)



(b)

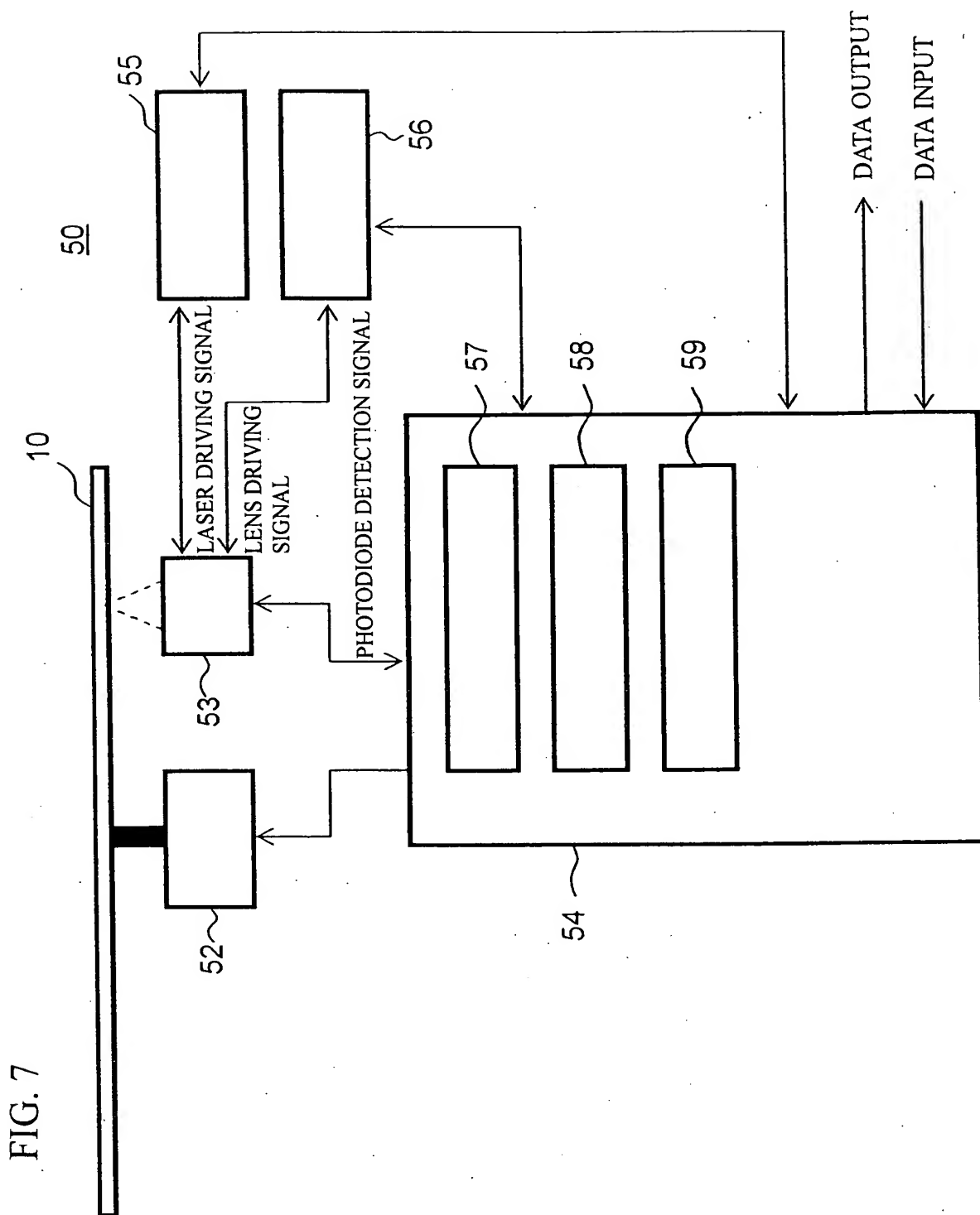


FIG. 8

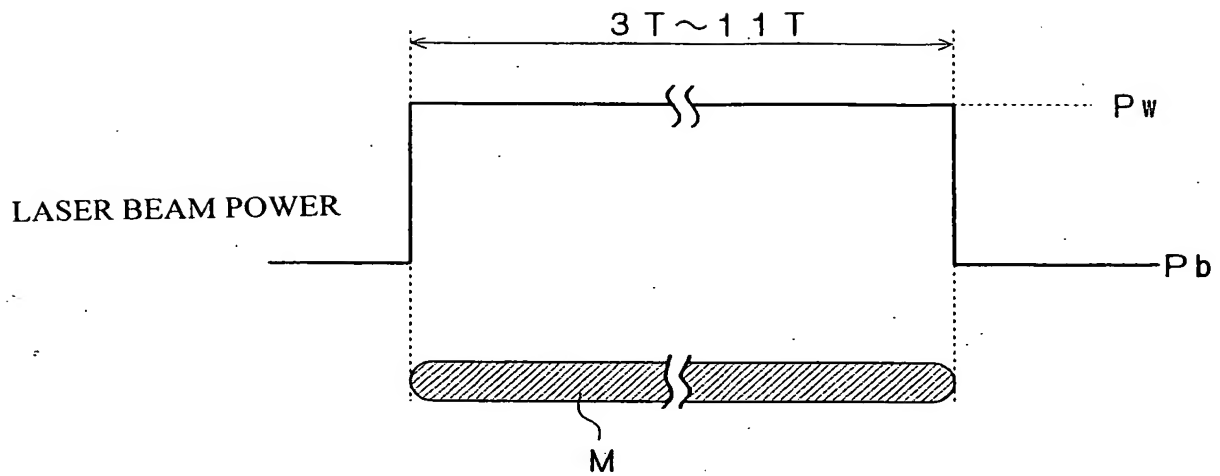
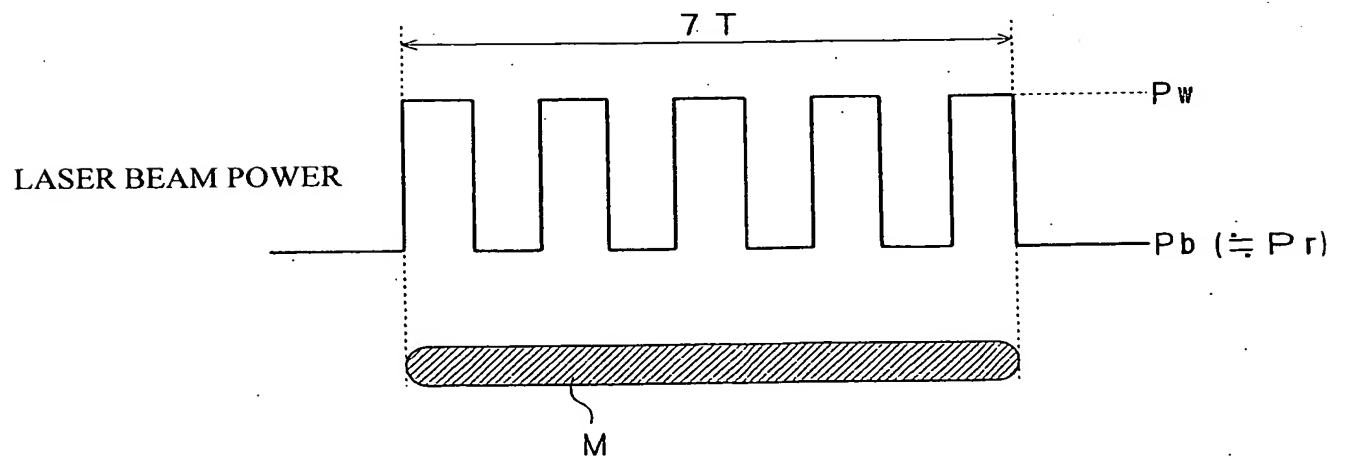


FIG. 9



- 5 2SPINDLE MOTOR
- 5 3HEAD
- 5 4CONTROLLER
- 5 5LASER DRIVE CIRCUIT
- 5 6LENS DRIVE CIRCUIT
- 5 7FOCUSING SERVO CIRCUIT
- 5 8TRACKING SERVO CIRCUIT
- 5 9LASER CONTROL CIRCUIT